# TWIST GEOMETRY OF ELEMENTARY DEFORMATIONS 

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Happy Birthday, Helga Baum!

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## Outline

(1) Twist construction
(2) HyperKÄHLER MODIfications

HyperKähler geometry
HyperKähler modifications
Double fibration
(3) Elementary deformations Tri-holomorphic actions Rotating actions

## Twist construction



- $P \rightarrow M$ a principal $S^{1}$-bundle, symmetry $Y$, connection 1-form $\theta$, curvature $\operatorname{pr}_{M}^{*} F=d \theta$
- $X \in \mathfrak{X}(M)$ generating $S^{1}$-action preserving $F$
- $X^{\prime}=\tilde{X}+a Y$ on $P$ preserving $\theta$ and $Y: \tilde{X} \in \mathcal{H}=\operatorname{ker} \theta$, $\left(\mathrm{pr}_{M}\right)_{*} \tilde{X}=X$, and $\left.d a=-X\right\lrcorner F$
- $W=P / X^{\prime}$, has action induced by $Y$


## Twist data

## Twist data

- $M$ manifold
- $X \in \mathfrak{X}(M)$, circle action
- $F \in \Omega_{\mathbb{Z}}^{2}(M)^{X}$
- $a \in C^{\infty}(M)$ with $\left.d a=-X\right\lrcorner F$

horizontal distribution $\mathcal{H}=\operatorname{ker} \theta \subset T P$


## DEFINITION

$\alpha$ tensor on $M$ is $\mathcal{H}$-related to $\alpha_{W}$ on $W$ if

$$
\operatorname{pr}_{M}^{*} \alpha=\operatorname{pr}_{W}^{*} \alpha_{W} \quad \text { on } \mathcal{H}
$$

Write $\alpha \sim_{\mathcal{H}} \alpha_{W}$

## Twist computations

$\alpha \sim_{\mathcal{H}} \alpha_{W}$ if $\operatorname{pr}_{M}^{*} \alpha=\operatorname{pr}_{W}^{*} \alpha_{W}$ on $\mathcal{H}=\operatorname{ker} \theta$

- $\alpha \in \Omega^{p}(M)$ :


$$
\left.d \alpha_{W} \sim_{\mathcal{H}} d_{W} \alpha:=d \alpha-\frac{1}{a} F \wedge(X\lrcorner \alpha\right)
$$

- I complex structure on $M$ : $I_{W}$ integrable if and only if $F \in \Lambda_{I}^{1,1}$


## Example

$M=M(n):=\mathbb{C P}{ }^{n} \times T^{2}$ Kähler, $X$ on $T^{2}, F=\omega_{\mathrm{FS}}$ :
$W=S^{2 n+1} \times S^{1}$ non-Kähler.
How can we get Kähler, hyperKähler,... ?

## HyperKÄHler geometry

$M^{4 n}$ hyperKähler: $g$ (pseudo-)Riemannian metric, $I, J, K: T M \rightarrow T M$ bundle endomorphisms with

- $I^{2}=-1=J^{2}=K^{2}, I J=K=-J I$
- $g(I X, I Y)=g(X, Y)$ etc. and
- $\omega_{I}(X, Y)=g(I X, Y)$ etc. satisfy

$$
d \omega_{I}=0=d \omega_{J}=d \omega_{K}
$$

Then

- $g$ is Ricci-flat,
- $\operatorname{Hol}_{0}(g) \leqslant S p(n)$ and
- I, J, K are integrable.


## HyperKÄhler quotients

Suppose $X$ is a tri-holomorphic isometry of $(M, g, I, J, K)$, $L_{X} g=0, L_{X} I=0=L_{X} J=L_{X} K$, generating a circle action.

A hyperKähler moment map for $X$ is $\mu=\left(\mu_{I}, \mu_{J}, \mu_{K}\right): M \rightarrow \mathbb{R}^{3}$ such that

$$
\left.\left.\left.d \mu=(X\lrcorner \omega_{I}, X\right\lrcorner \omega_{J}, X\right\lrcorner \omega_{K}\right)
$$

$X$ is then tri-Hamiltonian

## Theorem (Hitchin, Karlhede, Lindström and Roček 1987)

If $X$ acts freely on $\mu^{-1}(0)$, then

$$
M / / / X=\mu^{-1}(0) / X
$$

is a smooth hyperKähler manifold of dimension $\operatorname{dim} M-4$.

## HyperKÄhler modifications

## Definition (Dancer-S)

The hyperKähler modification of $M$ is

$$
M_{\mathrm{mod}}=(M \times \mathbb{H}) / / /\left(X^{\prime}=X-\frac{\partial}{\partial \theta}\right)
$$

where $\frac{\partial}{\partial \theta}$ generates $q \mapsto e^{i \theta} q$ on $\mathbb{H}=\mathbb{R}^{4}$.

- $\operatorname{dim} M_{\text {mod }}=\operatorname{dim} M$
- $M$ complete, then $M_{\text {mod }}$ complete
- $\pi_{1}(M)=0$, then $b_{2}\left(M_{\text {mod }}\right)=b_{2}(M)+1$


## Example

$M=\mathbb{H}, X=\frac{\partial}{\partial \theta}, \mu=\mu_{\mathbb{H}}+c, c \neq 0: \quad M_{\bmod }=T^{*} \mathrm{CP}(1)$
Which hyperKähler metrics are modifications?

## A double fibration

For $\Phi=\mu-\mu_{\mathbb{H}}, X^{\prime}=X-\frac{\partial}{\partial \theta}$ :

$$
P=\Phi^{-1}(0) \xrightarrow{\iota} M \times \mathbb{H}
$$



- $\operatorname{pr}\left(X^{\prime}\right)$ is a Riemannian submersion for $\iota^{*}\left(g+g_{\mathbb{H}}\right)$
- $\mathrm{pr}_{1}$ is not a Riemannian submersion, it induces the metric $g^{N}$ on $M$ :

$$
\begin{aligned}
& g^{N}=g+\frac{1}{2\|\mu\|} g_{\alpha}, \quad g_{\alpha}=\alpha_{0}^{2}+\alpha_{I}^{2}+\alpha_{J}^{2}+\alpha_{K}^{2} \\
& \alpha_{0}=X^{b}=g(X, \cdot), \alpha_{I}=I \alpha_{0}=-\alpha_{0}(I \cdot) \text { etc. }
\end{aligned}
$$

## Elementary deformations

$g$ hyperKähler, $X$ an isometry, $\alpha_{0}=X^{b}, g_{\alpha}=\alpha_{0}^{2}+\alpha_{I}^{2}+\alpha_{J}^{2}+\alpha_{K}^{2}$

## Definition

An elementary deformation $g^{N}$ of $g$ with respect to $X$ is

$$
g^{N}=f g+h g_{\alpha}
$$

for some $f, h \in C^{\infty}(M)$
There are only two cases for $X$
(1) tri-holomorphic: $L_{X} I=0=L_{X} J=L_{X} K$
(2) rotating: $L_{X} I=0, L_{X} J=K$

## Tri-holomorphic actions

$g$ hyperKähler, $X$ tri-holomorphic, $\operatorname{dim} M>4$
Locally $X$ is tri-Hamiltonian with moment map $\mu=\left(\mu_{I}, \mu_{J}, \mu_{K}\right)$

## Theorem (S)

An elementary deformation $g^{N}=f g+h g_{\alpha}$ twists via $(X, F, a)$ to a hyperKähler metric $g_{W}$ if and only if

- $f$ constant, so take $f \equiv 1$,
- $h=h\left(\mu_{I}, \mu_{J}, \mu_{K}\right)$ is harmonic
- $F=d\left(h \alpha_{0}\right)+*_{3} d h$
- $a=1+h\|X\|^{2} \neq 0$

Proof method
(1) $\omega_{I}^{N} \sim_{\mathcal{H}} \omega_{I}^{N}=$ $f \omega_{I}+h \omega_{I}^{\alpha}$
(2) impose $d \omega_{I}^{W}=0$, i.e. $d_{W} \omega_{I}^{N}=0$
(3) impose $d a=-X\lrcorner F$
(4) impose $d F=0$
$g$ hyperKähler, $X$ tri-Hamiltonian, $g^{N}=g+h g_{\alpha}, h$ harmonic

## Example

HyperKähler modification is $h=1 /(2\|\mu\|)$

## Example

Taub-NUT deformation $W=\left(M \times\left(S^{1} \times \mathbb{R}^{3}\right)\right) / / / S^{1}$, diffeomorphic to $M$, is $h \equiv 1$

## Example

$h>0: Z^{4}, g_{Z}(h)=\frac{1}{h}(d t+\omega)^{2}+h\left(d x^{2}+d y^{2}+d z^{2}\right), d \omega=*_{3} d h$ is a general hyperKähler 4-manifold with free tri-Hamiltonian action and $W=(M \times Z) / / / S^{1}$

## Inversion

Generally: Twist of $M$ by data $(X, F, a)$ to $W$ is inverted by twist data on $W \mathcal{H}$-related to $\left(\frac{1}{a} X,-\frac{1}{a} F, \frac{1}{a}\right)$.

## Proposition (S)

HyperKähler twists above of the elementary deformation $g^{N}=g+h g_{\alpha}$ of $g$ corresponding to $h$ is inverted by the elementary deformation of $g_{W}$ corresponding to $-h$.

- Modification inverted by $h=-1 /(2\|\mu\|)$. To get positive definite, need $\|X\|^{2}<2\|\mu\|$. So flat $\mathbb{R}^{4}$ is not a modification.
- Taub-NUT deformation if and only if $\|X\|$ is bounded.
- $h>0$ : inversion corresponds to hyperKähler quotient of
$\left(M \times Z^{4}, g \times-g_{Z}(h)\right)$. quaternionic Lorentzian


## Strong HKT

strong HKT: $(g, I, J, K)$ with

- $I d \omega_{I}=J d \omega_{J}=K d \omega_{K}=:-c$ and
- $d c=0$


## Proposition

$g$ hyperKähler, $X$ tri-Hamiltonian, rank $d \alpha_{0} \geqslant 16$. An elementary deformation $g^{N}=f g+h g_{\alpha}$ twists via $(X, F, a)$ to a strong HKT metric $g_{W}$ if and only if

- $f$ constant, so take $f \equiv 1$,
- $h=h\left(\mu_{I}, \mu_{J}, \mu_{K}\right)$ is harmonic
- $F=d\left(h \alpha_{0}\right)$
- $a=1+h\|X\|^{2} \neq 0$

Cf. hyperKähler twist $F=d\left(h \alpha_{0}\right)+*_{3} d h$.

## Rotating actions

$g$ hyperKähler, $\operatorname{dim} M>4, L_{X} I=0, L_{X} J=K$
Locally there is a Kähler moment map $\mu: M \rightarrow \mathbb{R}$ for $\left(\omega_{I}, X\right)$.

## Theorem (MaciÁ-S)

For $X$ non-null, an elementary deformation $g^{N}=f g+h g_{\alpha}$ twists to quaternionic Kähler if and only if

- $f=1 /(\mu-c)$
- $h=-1 /(\mu-c)^{2}$
- $F=d \alpha_{0}+\omega_{I}$
- $a=\|X\|^{2}-\mu+c$

This is the $\mathrm{hK} / \mathrm{qK}$ correspondence Haydys 2008; Alexandrov, Persson and Pioline 2011; Hitchin 2013; Alekseevsky, Cortés, Dyckmanns and Mohaupt 2013. In the c-map context, $g$ has signature $(4 n, 4)$, but $g^{N}$ is positive definite.

Show quaternionic Kähler by $d \Omega=0$

$$
\Omega=\omega_{I}^{2}+\omega_{J}^{2}+\omega_{K}^{2}
$$

provided $\operatorname{dim} M \geqslant 12$.
For $\operatorname{dim} M=8$, show

$$
d\left(\begin{array}{c}
\omega_{I} \\
\omega_{J} \\
\omega_{K}
\end{array}\right)=A \wedge\left(\begin{array}{c}
\omega_{I} \\
\omega_{J} \\
\omega_{K}
\end{array}\right)
$$

for some $A \in \Omega^{1} \otimes \mathfrak{s o}(3)$.

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